## SIEMENS

## Data sheet

## 6ES7515-2AM01-0AB0



\*\*\* Spare part \*\*\* SIMATIC S7-1500, CPU 1515-2 PN, central processing unit with work memory 500 KB for program and 3 MB for data, 1st interface: PROFINET IRT with 2-port switch, 2nd interface: PROFINET RT, 30 ns bit performance, SIMATIC Memory Card required

| General information  |  |
|--|--|
| Product type designation   | CPU 1515-2 PN  |
| HW functional status   | FS03   |
| Firmware version   | V2.9   |
| Product function   |  |
| I&M data   | Yes; I&M0 to I&M3  |
| Isochronous mode   | Yes; Distributed and central; with minimum OB 6x cycle of 500 $\mu s$ (distributed) and 1 ms (central) |
| Engineering with   |  |
| <ul> <li>STEP 7 TIA Portal configurable/integrated from<br/>version</li> </ul> | V17 (FW V2.9) / V13 (FW V1.5) or higher  |
| Configuration control  |  |
| via dataset  | Yes  |
| Display  |  |
| Screen diagonal [cm]   | 6.1 cm   |
| Control elements   |  |
| Number of keys   | 6  |
| Mode selector switch   | 1  |
| Supply voltage   |  |
| Rated value (DC)   | 24 V   |
| permissible range, lower limit (DC)  | 19.2 V   |
| permissible range, upper limit (DC)  | 28.8 V   |
| Reverse polarity protection  | Yes  |
| Mains buffering  |  |
| <ul> <li>Mains/voltage failure stored energy time</li> </ul>                   | 5 ms   |
| Repeat rate, min.  | 1/s  |
| Input current  |  |
| Current consumption (rated value)  | 0.8 A  |
| Inrush current, max.   | 2.4 A; Rated value   |
| l²t  | 0.02 A <sup>2</sup> ·s   |
| Power  |  |
| Infeed power to the backplane bus  | 12 W   |
| Power consumption from the backplane bus (balanced)                            | 6.2 W  |
| Power loss   |  |
| Power loss, typ.   | 6.3 W  |
| Memory   |  |
| Number of slots for SIMATIC memory card  | 1  |
| SIMATIC memory card required   | Yes  |
| Work memory  |  |
| <ul> <li>integrated (for program)</li> </ul>                                   | 500 kbyte  |

| <ul> <li>integrated (for data)</li> </ul>                      | 3 Mbyte   |
|--|---|
| Load memory  |   |
| <ul> <li>Plug-in (SIMATIC Memory Card), max.</li> </ul>        | 32 Gbyte  |
| Backup   |   |
| maintenance-free   | Yes   |
| CPU processing times   |   |
| for bit operations, typ.                                       | 30 ns   |
| for word operations, typ.                                      | 36 ns   |
| for fixed point arithmetic, typ.                               | 48 ns   |
| for floating point arithmetic, typ.                            | 192 ns  |
| CPU-blocks   |   |
|  | 8 000: Blocks (OR ER EC DR) and LIDTs   |
| Number of elements (total) DB                                  | 8 000; Blocks (OB, FB, FC, DB) and UDTs   |
| Number range   | 1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999 |
| • Size, max.   | 3 Mbyte; For DBs with absolute addressing, the max. size is 64 KB   |
| FB   |   |
| Number range   | 0 65 535  |
| • Size, max.   | 500 kbyte   |
| FC   |   |
| Number range   | 0 65 535  |
| • Size, max.   | 500 kbyte   |
| OB   |   |
| • Size, max.   | 500 kbyte   |
| <ul> <li>Number of free cycle OBs</li> </ul>                   | 100   |
| <ul> <li>Number of time alarm OBs</li> </ul>                   | 20  |
| <ul> <li>Number of delay alarm OBs</li> </ul>                  | 20  |
| <ul> <li>Number of cyclic interrupt OBs</li> </ul>             | 20; With minimum OB 3x cycle of 500 µs  |
| <ul> <li>Number of process alarm OBs</li> </ul>                | 50  |
| <ul> <li>Number of DPV1 alarm OBs</li> </ul>                   | 3   |
| <ul> <li>Number of isochronous mode OBs</li> </ul>             | 2   |
| <ul> <li>Number of technology synchronous alarm OBs</li> </ul> | 2   |
| Number of startup OBs  | 100   |
| <ul> <li>Number of asynchronous error OBs</li> </ul>           | 4   |
| Number of synchronous error OBs                                | 2   |
| Number of diagnostic alarm OBs                                 | 1   |
| Nesting depth  |   |
| <ul> <li>per priority class</li> </ul>                         | 24  |
| Counters, timers and their retentivity                         |   |
| S7 counter   |   |
| Number   | 2 048   |
| Retentivity  | 2 010   |
| — adjustable   | Yes   |
| IEC counter  |   |
| Number   | Any (only limited by the main memory)   |
| Retentivity  | , any terms intrace by the main memory)   |
| — adjustable   | Yes   |
| S7 times   |   |
| Number   | 2 048   |
| Retentivity  |   |
| — adjustable   | Yes   |
| IEC timer  |   |
| Number   | Any (only limited by the main memory)   |
| Retentivity  |   |
| — adjustable   | Yes   |
|  |   |
| Data areas and their retentivity                               |   |
| Retentive data area (incl. timers, counters, flags), max.      | 512 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 472 KB               |
| Extended retentive data area (incl. timers, counters, flags),  | 3 Mbyte; When using PS 6 0W 24/48/60 V DC HF  |
| max.   |   |
| Flag   |   |
| • Size, max.   | 16 kbyte  |
| Number of clock memories                                       | 8; 8 clock memory bit, grouped into one clock memory byte   |
|  |   |

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| Data blocks  |   |
|--|---|
| Retentivity adjustable   | Yes   |
| Retentivity preset   | No  |
| Local data   |   |
| <ul> <li>per priority class, max.</li> </ul>                             | 64 kbyte; max. 16 KB per block  |
| Address area   |   |
| Number of IO modules   | 8 192; max. number of modules / submodules  |
| I/O address area   |   |
| Inputs   | 32 kbyte; All inputs are in the process image   |
| Outputs  | 32 kbyte; All outputs are in the process image  |
| per integrated IO subsystem  |   |
| — Inputs (volume)  | 8 kbyte   |
| — Outputs (volume)   | 8 kbyte   |
| per CM/CP  | 9 kbyta   |
| — Inputs (volume)<br>— Outputs (volume)                                  | 8 kbyte<br>8 kbyte  |
| Subprocess images  | 0 KDyte   |
| Number of subprocess images, max.  | 32  |
| Hardware configuration   |   |
| Number of distributed IO systems   | 64: A distributed I/O system is characterized not only by the integration   |
|  | of distributed I/O via PROFINET or PROFIBUS communication<br>modules, but also by the connection of I/O via AS-i master modules or<br>links (e.g. IE/PB-Link) |
| Number of DP masters   |   |
| • Via CM   | 8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can<br>be inserted in total  |
| Number of IO Controllers   |   |
| integrated   | 2   |
| • Via CM   | 8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can<br>be inserted in total  |
| Rack   |   |
| <ul> <li>Modules per rack, max.</li> </ul>                               | 32; CPU + 31 modules  |
| <ul> <li>Number of lines, max.</li> </ul>                                | 1   |
| PtP CM   |   |
| Number of PtP CMs  | the number of connectable PtP CMs is only limited by the number of available slots  |
| Time of day  |   |
| Clock  |   |
| • Туре   | Hardware clock  |
| Backup time  | 6 wk; At 40 °C ambient temperature, typically   |
| Deviation per day, max.  | 10 s; Typ.: 2 s   |
| Operating hours counter<br>• Number                                      | 16  |
| Clock synchronization  |   |
| supported  | Yes   |
| • in AS, master  | Yes   |
| • in AS, slave   | Yes   |
| on Ethernet via NTP  | Yes   |
| Interfaces   |   |
| Number of PROFINET interfaces  | 2   |
| 1. Interface   |   |
| Interface types  |   |
| RJ 45 (Ethernet)   | Yes; X1   |
| Number of ports  | 2   |
| integrated switch  | Yes   |
| Protocols  |   |
| IP protocol  | Yes; IPv4   |
| PROFINET IO Controller   | Yes   |
| PROFINET IO Device     SIMATIC communication                             | Yes   |
| <ul> <li>SIMATIC communication</li> <li>Open IE communication</li> </ul> | Yes   |
| Web server   | Yes; Optionally also encrypted<br>Yes   |
| Media redundancy   | Yes   |
| PROFINET IO Controller   |   |

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| Services  |   |
|---|---|
| — PG/OP communication   | Yes   |
| — Isochronous mode  | Yes   |
| — Direct data exchange  | Yes; Requirement: IRT and isochronous mode (MRPD optional)  |
| — IRT   | Yes   |
| - PROFlenergy   | Yes; per user program   |
| — Prioritized startup   | Yes; Max. 32 PROFINET devices   |
| <ul> <li>Number of connectable IO Devices, max.</li> </ul>  | 256; In total, up to 1 000 distributed I/O devices can be connected via   |
|   | AS-i, PROFIBUS or PROFINET  |
| <ul> <li>— Of which IO devices with IRT, max.</li> </ul>  | 64  |
| <ul> <li>— Number of connectable IO Devices for RT,</li> </ul>  | 256   |
| max.  |   |
| <ul> <li>— of which in line, max.</li> </ul>  | 256   |
| <ul> <li>— Number of IO Devices that can be</li> </ul>  | 8; in total across all interfaces   |
| simultaneously activated/deactivated, max.  |   |
| <ul> <li>— Number of IO Devices per tool, max.</li> </ul>   | 8   |
| — Updating times  | The minimum value of the update time also depends on communication  |
|   | share set for PROFINET IO, on the number of IO devices, and on the  |
| Lindete time for IDT  | quantity of configured user data  |
| Update time for IRT   | 250 up to 4 may Nate: In the same of IDT with its share are deal.   |
| — for send cycle of 250 µs  | 250 μs to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 μs of the isochronous OB is decisive |
| — for send cycle of 500 µs  | 500 µs to 8 ms  |
| — for send cycle of 1 ms  | 1 ms to 16 ms   |
| — for send cycle of 2 ms  | 2 ms to 32 ms   |
|   | 4 ms to 64 ms   |
| <ul> <li>for send cycle of 4 ms</li> <li>With IRT and parameterization of "odd" send</li> </ul>   | Update time = set "odd" send clock (any multiple of 125 μs: 375 μs, 625   |
| cycles  | $\mu$ s 3 875 $\mu$ s)  |
| Update time for RT  |   |
| — for send cycle of 250 μs  | 250 μs to 128 ms  |
| — for send cycle of 500 μs  | 500 μs to 256 ms  |
| — for send cycle of 1 ms  | 1 ms to 512 ms  |
| — for send cycle of 2 ms  | 2 ms to 512 ms  |
| -   | 4 ms to 512 ms  |
| — for send cycle of 4 ms     PROFINET IO Device   | 4 115 10 5 12 115   |
| Services  |   |
| — PG/OP communication   | Yes   |
| — Isochronous mode  | No  |
| — IRT   | Yes   |
| — PROFlenergy   |   |
|   | Yes; per user program<br>Yes  |
| — Shared device     Number of IO Controllers with shared device   | 4   |
| <ul> <li>Number of IO Controllers with shared device,<br/>max.</li> </ul>   | 4   |
| <ul> <li>— activation/deactivation of I-devices</li> </ul>  | Yes; per user program   |
| Asset management record   | Yes; per user program   |
| , in the second s |   |
| 2. Interface  |   |
| Interface types   |   |
| • RJ 45 (Ethernet)  | Yes; X2   |
| Number of ports   | 1   |
| integrated switch   | No  |
| Protocols   |   |
| • IP protocol   | Yes; IPv4   |
| PROFINET IO Controller  | Yes   |
| PROFINET IO Device  | Yes   |
| <ul> <li>SIMATIC communication</li> </ul>   | Yes   |
| Open IE communication   | Yes; Optionally also encrypted  |
| Web server  | Yes   |
| Media redundancy  | No  |
| PROFINET IO Controller  |   |
| Services  |   |
| — PG/OP communication   | Yes   |
| — Isochronous mode  | No  |
| — Direct data exchange  | No  |
| — IRT   | No  |
| - PROFlenergy   | Yes; per user program   |
|   |   |

| — Prioritized startup  | No   |
|--|--|
| <ul> <li>Number of connectable IO Devices, max.</li> </ul>   | 32; In total, up to 1 000 distributed I/O devices can be connected via   |
| <ul> <li>— Number of connectable IO Devices for RT,</li> </ul>   | AS-i, PROFIBUS or PROFINET<br>32   |
| max.   | JZ   |
| — of which in line, max.   | 32   |
| — Number of IO Devices that can be   | 8; in total across all interfaces  |
| simultaneously activated/deactivated, max.   |  |
| <ul> <li>— Number of IO Devices per tool, max.</li> </ul>  | 8  |
| — Updating times   | The minimum value of the update time also depends on communication   |
|  | share set for PROFINET IO, on the number of IO devices, and on the   |
| Update time for RT   | quantity of configured user data   |
| — for send cycle of 1 ms   | 1 ms to 512 ms   |
| PROFINET IO Device   | 1 113 10 3 12 113  |
| Services   |  |
| — PG/OP communication  | Yes  |
| — Isochronous mode   | No   |
| — IRT  | No   |
| — PROFlenergy  | Yes; per user program  |
| — Prioritized startup  | No   |
| — Shared device  | Yes  |
| — Number of IO Controllers with shared device,   | 4  |
| max.   |  |
| - activation/deactivation of I-devices   | Yes; per user program  |
| <ul> <li>Asset management record</li> </ul>  | Yes; per user program  |
| Interface types  |  |
| RJ 45 (Ethernet)   |  |
| • 100 Mbps   | Yes  |
| Autonegotiation  | Yes  |
| Autocrossing   | Yes  |
| <ul> <li>Industrial Ethernet status LED</li> </ul>   | Yes  |
|  |  |
| Protocols  |  |
| Protocols<br>PROFIsafe   | No   |
|  | No   |
| PROFIsafe  | No<br>192; via integrated interfaces of the CPU and connected CPs / CMs  |
| PROFIsafe<br>Number of connections   |  |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.  | 192; via integrated interfaces of the CPU and connected CPs / CMs  |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.<br>• Number of connections reserved for ES/HMI/web   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10  |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.<br>• Number of connections reserved for ES/HMI/web<br>• Number of connections via integrated interfaces  | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108   |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.<br>• Number of connections reserved for ES/HMI/web<br>• Number of connections via integrated interfaces<br>• Number of S7 routing paths  | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108   |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.<br>• Number of connections reserved for ES/HMI/web<br>• Number of connections via integrated interfaces<br>• Number of S7 routing paths<br>Redundancy mode   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16   |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.<br>• Number of connections reserved for ES/HMI/web<br>• Number of connections via integrated interfaces<br>• Number of S7 routing paths<br>Redundancy mode<br>• H-Sync forwarding  | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16   |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.<br>• Number of connections reserved for ES/HMI/web<br>• Number of connections via integrated interfaces<br>• Number of S7 routing paths<br>Redundancy mode<br>• H-Sync forwarding<br>Media redundancy  | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP   |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.<br>• Number of connections reserved for ES/HMI/web<br>• Number of connections via integrated interfaces<br>• Number of S7 routing paths<br>Redundancy mode<br>• H-Sync forwarding<br>Media redundancy<br>— Media redundancy<br>— MRP   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client  |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.<br>• Number of connections reserved for ES/HMI/web<br>• Number of connections via integrated interfaces<br>• Number of S7 routing paths<br>Redundancy mode<br>• H-Sync forwarding<br>Media redundancy<br>— Media redundancy<br>— MRP<br>— MRP interconnection, supported   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0  |
| PROFIsafe<br>Number of connections<br>• Number of connections, max.<br>• Number of connections reserved for ES/HMI/web<br>• Number of connections via integrated interfaces<br>• Number of S7 routing paths<br>Redundancy mode<br>• H-Sync forwarding<br>Media redundancy<br>— Media redundancy<br>— MRP<br>— MRP<br>— MRP interconnection, supported<br>— MRPD  | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT   |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         — Media redundancy         — MRP         — MRP         — MRP interconnection, supported         — MRPD         — Switchover time on line break, typ.   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD   |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - Media redundancy         - MRP         - MRP         - MRP         - MRPD         - Switchover time on line break, typ.         - Number of stations in the ring, max.   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT   |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         — Media redundancy         — MRP         — MRP         — MRP         — Switchover time on line break, typ.         — Number of stations in the ring, max.         SIMATIC communication  | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50   |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         — Media redundancy         — MRP         — MRP         — MRP         — Switchover time on line break, typ.         — Number of stations in the ring, max.         SIMATIC communication         • PG/OP communication  | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50<br>Yes; encryption with TLS V1.3 pre-selected   |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         — Media redundancy         — MRP         — MRP         — MRP         — Switchover time on line break, typ.         — Number of stations in the ring, max.         SIMATIC communication         • S7 routing   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50<br>Yes; encryption with TLS V1.3 pre-selected<br>Yes  |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - Media redundancy         - MRP         - MRP         - MRP         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50<br>Yes; encryption with TLS V1.3 pre-selected<br>Yes<br>Yes   |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         — Media redundancy         — MRP         — MRP         — MRP         — Switchover time on line break, typ.         — Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server         • S7 communication, as client   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50<br>Yes; encryption with TLS V1.3 pre-selected<br>Yes<br>Yes<br>Yes  |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         — MRP         — MRP         — MRP         — Switchover time on line break, typ.         — Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server         • S7 communication, as client         • User data per job, max.  | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50<br>Yes; encryption with TLS V1.3 pre-selected<br>Yes<br>Yes   |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - Media redundancy         - MRP         MRP interconnection, supported         - MRP         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server         • S7 communication, as client         • User data per job, max.         Open IE communication  | <ul> <li>192; via integrated interfaces of the CPU and connected CPs / CMs</li> <li>10</li> <li>108</li> <li>16</li> <li>Yes</li> <li>only via 1st interface (X1)</li> <li>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client</li> <li>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0</li> <li>Yes; Requirement: IRT</li> <li>200 ms; For MRP, bumpless for MRPD</li> <li>50</li> <li>Yes; encryption with TLS V1.3 pre-selected</li> <li>Yes</li> <li>Yes</li> <li>See online help (S7 communication, user data size)</li> </ul>  |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - MRP         MRP         - MRP         - MRP         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server         • S7 communication, as client         • User data per job, max.         Open IE communication         • TCP/IP   | <ul> <li>192; via integrated interfaces of the CPU and connected CPs / CMs</li> <li>10</li> <li>108</li> <li>16</li> <li>Yes</li> <li>only via 1st interface (X1)</li> <li>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client</li> <li>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0</li> <li>Yes; Requirement: IRT</li> <li>200 ms; For MRP, bumpless for MRPD</li> <li>50</li> <li>Yes; encryption with TLS V1.3 pre-selected</li> <li>Yes</li> <li>Yes</li> <li>See online help (S7 communication, user data size)</li> </ul>  |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - Media redundancy         - MRP         - MRP         - MRP         - MRPD         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server         • S7 communication, as client         • User data per job, max.         Open IE communication         • TCP/IP         - Data length, max.   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50<br>Yes; encryption with TLS V1.3 pre-selected<br>Yes<br>Yes<br>See online help (S7 communication, user data size)<br>Yes<br>64 kbyte  |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - MRP         MRP         - MRP         - MRP         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server         • S7 communication, as client         • User data per job, max.         Open IE communication         • TCP/IP   | <ul> <li>192; via integrated interfaces of the CPU and connected CPs / CMs</li> <li>10</li> <li>108</li> <li>16</li> <li>Yes</li> <li>only via 1st interface (X1)</li> <li>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP Manager; MRP Client</li> <li>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0</li> <li>Yes; Requirement: IRT</li> <li>200 ms; For MRP, bumpless for MRPD</li> <li>50</li> <li>Yes; encryption with TLS V1.3 pre-selected</li> <li>Yes</li> <li>Yes</li> <li>See online help (S7 communication, user data size)</li> </ul>  |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - MRP         - MRP         - MRP         - MRPD         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server         • S7 communication, as client         • User data per job, max.         Open IE communication         • TCP/IP         - Data length, max.         - several passive connections per port,  | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50<br>Yes; encryption with TLS V1.3 pre-selected<br>Yes<br>Yes<br>See online help (S7 communication, user data size)<br>Yes<br>64 kbyte  |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - MRP         - MRP         - MRP         - MRP         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server         • S7 communication, as client         • User data per job, max.         Open IE communication         • TCP/IP         - Data length, max.         - several passive connections per port, supported   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50<br>Yes; encryption with TLS V1.3 pre-selected<br>Yes<br>Yes<br>See online help (S7 communication, user data size)<br>Yes<br>64 kbyte<br>Yes   |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - MRP interconnection, supported         - MRPD         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 communication, as server         • S7 communication, as client         • User data per job, max.         Open IE communication         • TCP/IP         - Data length, max.         - several passive connections per port, supported         • ISO-on-TCP (RFC1006)   | 192; via integrated interfaces of the CPU and connected CPs / CMs<br>10<br>108<br>16<br>Yes<br>only via 1st interface (X1)<br>Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP<br>Manager; MRP Client<br>Yes; as MRP ring node according to IEC 62439-2 Edition 3.0<br>Yes; Requirement: IRT<br>200 ms; For MRP, bumpless for MRPD<br>50<br>Yes; encryption with TLS V1.3 pre-selected<br>Yes<br>Yes<br>See online help (S7 communication, user data size)<br>Yes<br>64 kbyte<br>Yes<br>Yes  |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - MRP         Media redundancy         - MRP         MRPD         - MRPD         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 routing         • S7 communication, as server         • S7 communication, as client         • User data per job, max.         Open IE communication         • TCP/IP         - Data length, max.         - several passive connections per port, supported         • ISO-on-TCP (RFC1006)         - Data length, max. | 192; via integrated interfaces of the CPU and connected CPs / CMs         10         108         16         Yes         only via 1st interface (X1)         Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP         Manager; MRP Client         Yes; as MRP ring node according to IEC 62439-2 Edition 3.0         Yes; Requirement: IRT         200 ms; For MRP, bumpless for MRPD         50         Yes; encryption with TLS V1.3 pre-selected         Yes         Yes         See online help (S7 communication, user data size)         Yes         Yes         64 kbyte         Yes         64 kbyte  |
| PROFIsafe         Number of connections         • Number of connections, max.         • Number of connections reserved for ES/HMI/web         • Number of connections via integrated interfaces         • Number of S7 routing paths         Redundancy mode         • H-Sync forwarding         Media redundancy         - Media redundancy         - MRP         - MRP         - MRPD         - Switchover time on line break, typ.         - Number of stations in the ring, max.         SIMATIC communication         • S7 communication, as server         • S7 communication, as client         • User data per job, max.         Open IE communication         • TCP/IP         - Data length, max.         - several passive connections per port, supported         • ISO-on-TCP (RFC1006)         - Data length, max.         • UDP                   | 192; via integrated interfaces of the CPU and connected CPs / CMs         10         108         16         Yes         only via 1st interface (X1)         Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP         Manager; MRP Client         Yes; as MRP ring node according to IEC 62439-2 Edition 3.0         Yes; Requirement: IRT         200 ms; For MRP, bumpless for MRPD         50         Yes; encryption with TLS V1.3 pre-selected         Yes         Yes         See online help (S7 communication, user data size)         Yes         Yes         64 kbyte         Yes         Yes |

| • DHCP   | Yes  |
|--|--|
|  |  |
| • DNS<br>• SNMP  | Yes<br>Yes   |
| • DCP  | Yes  |
| • LLDP   | Yes  |
| ELDF     Encryption  | Yes; Optional  |
| Web server   | res, Optional  |
| • HTTP   | Yes; Standard and user pages   |
| • HTTPS  | Yes; Standard and user pages   |
| OPC UA   |  |
| Runtime license required   | Yes; "Medium" license required   |
| OPC UA Client  | Yes  |
| <ul> <li>Application authentication</li> </ul>   | Yes  |
| — Security policies  | Available security policies: None, Basic128Rsa15, Basic256Rsa15,   |
|  | Basic256Sha256   |
| — User authentication  | "anonymous" or by user name & password   |
| — Number of connections, max.  | 10   |
| <ul> <li>number of nodes of the client interfaces,<br/>recommended max.</li> </ul>   | 2 000  |
| <ul> <li>— Number of elements for one call of<br/>OPC_UA_NodeGetHandleList/OPC_UA_ReadList/C<br/>max.</li> </ul>                 | 300  |
| <ul> <li>— Number of elements for one call of<br/>OPC_UA_NameSpaceGetIndexList, max.</li> </ul>                                  | 20   |
| <ul> <li>— Number of elements for one call of<br/>OPC_UA_MethodGetHandleList, max.</li> </ul>                                    | 100  |
| <ul> <li>number of simultaneous calls of the client<br/>instructions for session management, per<br/>connection, max.</li> </ul> | 1  |
| <ul> <li>number of simultaneous calls of the client<br/>instructions for data access, per connection, max.</li> </ul>            | 5  |
| — Number of registerable nodes, max.   | 5 000  |
| <ul> <li>— Number of registerable method calls of<br/>OPC_UA_MethodCall, max.</li> </ul>   | 100  |
| <ul> <li>— Number of inputs/outputs when calling<br/>OPC_UA_MethodCall, max.</li> </ul>  | 20   |
| OPC UA Server  | Yes; Data access (read, write, subscribe), method call, custom address space                             |
| <ul> <li>Application authentication</li> </ul>   | Yes  |
| — Security policies  | Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256                          |
| — User authentication  | "anonymous" or by user name & password   |
| — GDS support (certificate management)   | Yes  |
| — Number of sessions, max.   | 48   |
| <ul> <li>Number of accessible variables, max.</li> </ul>   | 100 000  |
| — Number of registerable nodes, max.   | 20 000   |
| <ul> <li>Number of subscriptions per session, max.</li> <li>Sampling interval min</li> </ul>                                     | 20<br>100 ms   |
| <ul> <li>— Sampling interval, min.</li> <li>— Publishing interval, min.</li> </ul>   | 200 ms   |
| — Number of server methods, max.   | 50   |
| <ul> <li>Number of inputs/outputs per server method,</li> </ul>  | 20   |
| max.   |  |
| <ul> <li>number of monitored items, recommended max.</li> </ul>  | 2 000; for 1 s sampling interval and 1 s send interval   |
| - Number of server interfaces, max.  | 10 of each "Server interfaces" / "Companion specification" type and 20 of the type "Reference namespace" |
| <ul> <li>— Number of nodes for user-defined server<br/>interfaces, max.</li> </ul>   | 5 000  |
| <ul> <li>Alarms and Conditions</li> </ul>  | Yes  |
| <ul> <li>— Number of program alarms</li> </ul>   | 200  |
| — Number of alarms for system diagnostics  | 100  |
| Further protocols  |  |
| MODBUS   | Yes; MODBUS TCP  |
| Isochronous mode   |  |
| Equidistance   | Yes  |
| S7 message functions   |  |
| Number of login stations for message functions, max.   | 64   |

| Program alarms  | Yes   |
|---|---|
| Number of configurable program messages, max.   | 10 000; Program messages are generated by the "Program_Alarm"   |
|   | block, ProDiag or GRAPH   |
| Number of loadable program messages in RUN, max.  | 5 000   |
| Number of simultaneously active program alarms  |   |
| <ul> <li>Number of program alarms</li> </ul>  | 800   |
| <ul> <li>Number of alarms for system diagnostics</li> </ul>   | 200   |
| <ul> <li>Number of alarms for motion technology objects</li> </ul>  | 160   |
| Test commissioning functions  |   |
| Joint commission (Team Engineering)   | Yes; Parallel online access possible for up to 8 engineering systems  |
| Status block  | Yes; Up to 8 simultaneously (in total across all ES clients)  |
| Single step   | Νο  |
| Number of breakpoints   | 8   |
| Status/control  | •   |
| Status/control variable   | Yes   |
| Variables   | Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters  |
| Number of variables, max.   |   |
| - of which status variables, max.   | 200; per job  |
| — of which control variables, max.  | 200; per job<br>200; per job  |
|   |   |
| Forcing   | Yes   |
| Forcing     Forcing     Forcing   |   |
| Forcing, variables  | Peripheral inputs/outputs   |
| Number of variables, max.   | 200   |
| Diagnostic buffer   | Vac   |
| • present   | Yes   |
| Number of entries, max.   | 3 200   |
| — of which powerfail-proof  | 500   |
| Traces  |   |
| <ul> <li>Number of configurable Traces</li> </ul>   | 4; Up to 512 KB of data per trace are possible  |
| Interrupts/diagnostics/status information   |   |
| Diagnostics indication LED  |   |
| RUN/STOP LED  | Yes   |
| ERROR LED   | Yes   |
|   |   |
| • MAINT LED   | Yes   |
|   | Yes<br>Yes  |
| <ul><li>MAINT LED</li><li>Connection display LINK TX/RX</li></ul>   |   |
| MAINT LED     Connection display LINK TX/RX Supported technology objects  | Yes   |
| <ul><li>MAINT LED</li><li>Connection display LINK TX/RX</li></ul>   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of  |
| MAINT LED     Connection display LINK TX/RX Supported technology objects  | Yes   |
| MAINT LED     Connection display LINK TX/RX Supported technology objects Motion Control   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool   |
| MAINT LED     Connection display LINK TX/RX Supported technology objects Motion Control     Number of available Motion Control resources for  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool   |
| MAINT LED     Connection display LINK TX/RX Supported technology objects Motion Control     Number of available Motion Control resources for technology objects   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool   |
| MAINT LED     Connection display LINK TX/RX  Supported technology objects  Motion Control      Number of available Motion Control resources for technology objects      Required Motion Control resources   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources         <ul> <li>— per speed-controlled axis</li> </ul> </li> </ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40  |
| MAINT LED     Connection display LINK TX/RX  Supported technology objects  Motion Control      Number of available Motion Control resources for technology objects      Required Motion Control resources   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources</li> <li>— per speed-controlled axis</li> <li>— per positioning axis</li> <li>— per synchronous axis</li> <li>— per external encoder</li> </ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160   |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> <li>Supported technology objects</li> <li>Motion Control</li> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources         <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> </ul> </li> </ul>   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80   |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources</li> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> </ul>   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20   |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> </li> </ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources</li> <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per external encoder</li> <li>per cam track</li> <li>per probe</li> <li>Positioning axis</li> </ul></ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per synchronous axis</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> </li> </ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> </ul> </li> </ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Per positioning axes at motion control</li> </ul> </li> </ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources</li> <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control</li> </ul></ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> <li>Supported technology objects</li> <li>Motion Control</li> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> </ul>   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> <li>Supported technology objects</li> <li>Motion Control</li> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> </ul>   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>20<br>160<br>40<br>7<br>14  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> <li>Supported technology objects</li> <li>Motion Control</li> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per speed-controlled axis</li> <li>per synchronous axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> </ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>40<br>80<br>20<br>160<br>40<br>7<br>14<br>Yes; Universal PID controller with integrated optimization  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources</li> <ul> <li>per speed-controlled axis</li> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> Controller <ul> <li>PID_Compact</li> <li>PID_3Step</li> </ul></ul>   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>40<br>80<br>20<br>160<br>40<br>7<br>14<br>Yes; Universal PID controller with integrated optimization<br>Yes; PID controller with integrated optimization for valves   |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> </ul> Supported technology objects Motion Control <ul> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources</li> <ul> <li>per speed-controlled axis</li> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> Controller <ul> <li>PID_Compact</li> <li>PID_Temp</li> </ul></ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>40<br>80<br>20<br>160<br>40<br>7<br>14<br>Yes; Universal PID controller with integrated optimization<br>Yes; PID controller with integrated optimization for valves   |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> <li>Supported technology objects</li> <li>Motion Control</li> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> <li>Controller <ul> <li>PID_Compact</li> <li>PID-Temp</li> </ul> </li> <li>Counting and measuring</li> <li>High-speed counter</li> </ul>   | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40<br>7<br>14<br>Yes; Universal PID controller with integrated optimization<br>Yes; PID controller with integrated optimization for valves<br>Yes; PID controller with integrated optimization for temperature  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> <li>Supported technology objects</li> <li>Motion Control</li> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> <li>Controller <ul> <li>PID_Compact</li> <li>PID_Temp</li> </ul> </li> <li>Counting and measuring</li> <li>High-speed counter</li> </ul>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40<br>7<br>14<br>Yes; Universal PID controller with integrated optimization<br>Yes; PID controller with integrated optimization for valves<br>Yes; PID controller with integrated optimization for temperature  |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> <li>Supported technology objects</li> <li>Motion Control</li> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> <li>Controller <ul> <li>PID_Compact</li> <li>PID_Temp</li> </ul> </li> <li>Counting and measuring</li> <li>High-speed counter</li> </ul> <li>Ambient temperature during operation</li>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40<br>7<br>14<br>Yes; Universal PID controller with integrated optimization<br>Yes; PID controller with integrated optimization<br>Yes; PID controller with integrated optimization for valves<br>Yes; PID controller with integrated optimization for temperature<br>Yes |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> <li>Supported technology objects</li> <li>Motion Control</li> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> <li>Controller <ul> <li>PID_Compact</li> <li>PID_Temp</li> </ul> </li> <li>Counting and measuring</li> <li>High-speed counter</li> </ul> <li>Ambient conditions</li> <li>Ambient temperature during operation</li> <li>horizontal installation, min.</li> | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40<br>7<br>14<br>Yes; Universal PID controller with integrated optimization<br>Yes; PID controller with integrated optimization for valves<br>Yes; PID controller with integrated optimization for temperature<br>Yes   |
| <ul> <li>MAINT LED</li> <li>Connection display LINK TX/RX</li> <li>Supported technology objects</li> <li>Motion Control</li> <li>Number of available Motion Control resources for technology objects</li> <li>Required Motion Control resources <ul> <li>per speed-controlled axis</li> <li>per positioning axis</li> <li>per external encoder</li> <li>per output cam</li> <li>per cam track</li> <li>per probe</li> </ul> </li> <li>Positioning axis <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> <li>Controller <ul> <li>PID_Compact</li> <li>PID_Temp</li> </ul> </li> <li>Counting and measuring</li> <li>High-speed counter</li> </ul> <li>Ambient conditions</li>  | Yes<br>Yes; Note: The number of technology objects affects the cycle time of<br>the PLC program; selection guide via the TIA Selection Tool<br>2 400<br>40<br>80<br>160<br>80<br>20<br>160<br>40<br>7<br>14<br>Yes; Universal PID controller with integrated optimization<br>Yes; PID controller with integrated optimization<br>Yes; PID controller with integrated optimization for valves<br>Yes; PID controller with integrated optimization for temperature<br>Yes |

| • vertical installation, min.                                     | 0°0  |
|---|--|
| • vertical installation, max.                                     | 40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off |
| Ambient temperature during storage/transportation                 |  |
| • min.  | -40 °C   |
| • max.  | 70 °C  |
| Altitude during operation relating to sea level                   |  |
| <ul> <li>Installation altitude above sea level, max.</li> </ul>   | 5 000 m; Restrictions for installation altitudes > 2 000 m, see manual                             |
| configuration / header  |  |
| configuration / programming / header                              |  |
| Programming language  |  |
| — LAD   | Yes  |
| — FBD   | Yes  |
| — STL   | Yes  |
| — SCL   | Yes  |
| — GRAPH   | Yes  |
| Know-how protection   |  |
| <ul> <li>User program protection/password protection</li> </ul>   | Yes  |
| <ul> <li>Copy protection</li> </ul>                               | Yes  |
| Block protection  | Yes  |
| Access protection   |  |
| <ul> <li>protection of confidential configuration data</li> </ul> | Yes  |
| <ul> <li>Password for display</li> </ul>                          | Yes  |
| <ul> <li>Protection level: Write protection</li> </ul>            | Yes  |
| <ul> <li>Protection level: Read/write protection</li> </ul>       | Yes  |
| <ul> <li>Protection level: Complete protection</li> </ul>         | Yes  |
| programming / cycle time monitoring / header                      |  |
| lower limit   | adjustable minimum cycle time  |
| upper limit   | adjustable maximum cycle time  |
| Dimensions  |  |
| Width   | 70 mm  |
| Height  | 147 mm   |
| Depth   | 129 mm   |
| Weights   |  |
| Weight, approx.   | 830 g  |